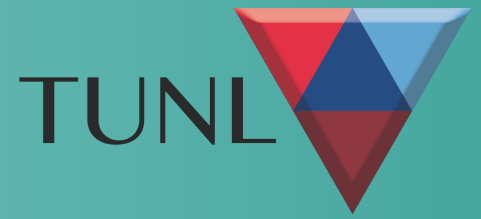


# Machine Learning—Examples from Particle Accelerators



**Y. K. Wu**

*TUNL and Duke University*

*January 30, 2020*

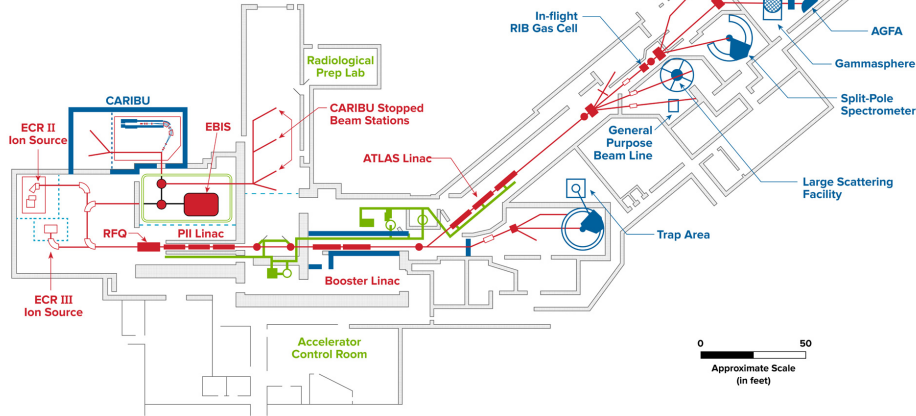
*Work supported by U.S. DOE Grant: DE-FG02-97ER41033*

# DoE Nuclear Physics User Facilities

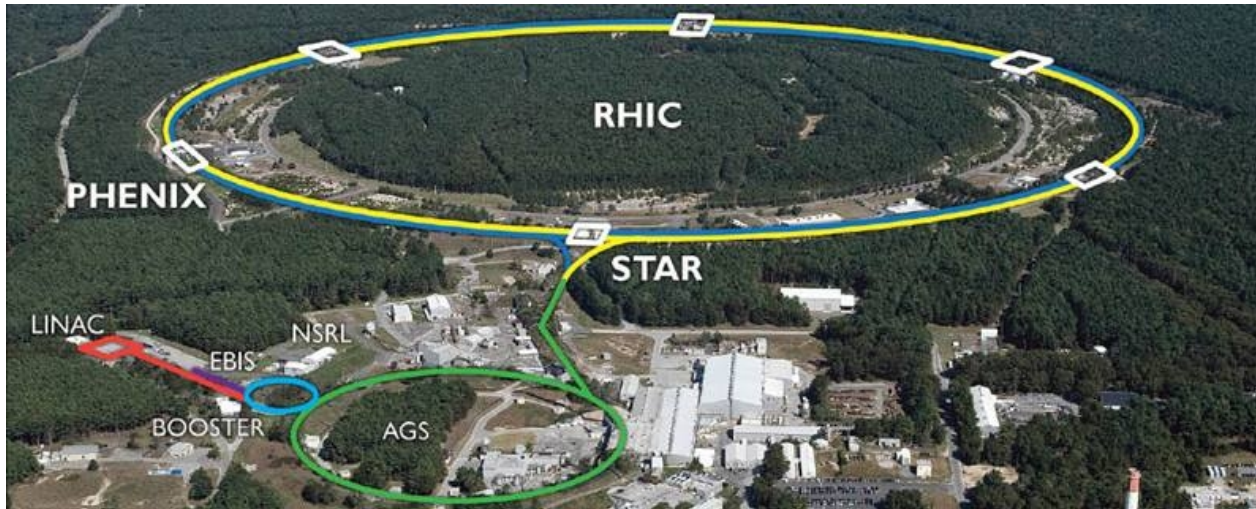
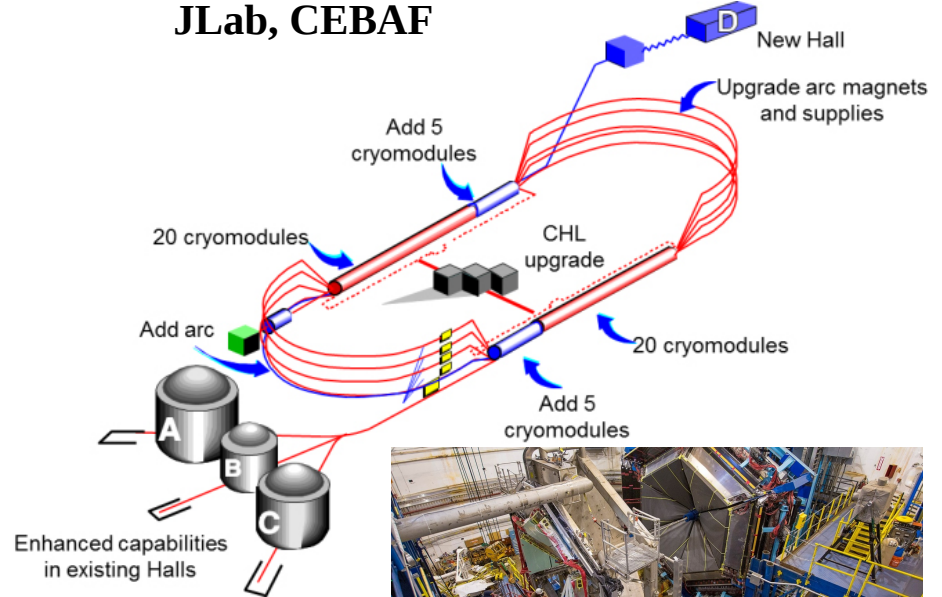


## ATLAS

ARGONNE TANDEM LINEAR ACCELERATOR SYSTEM



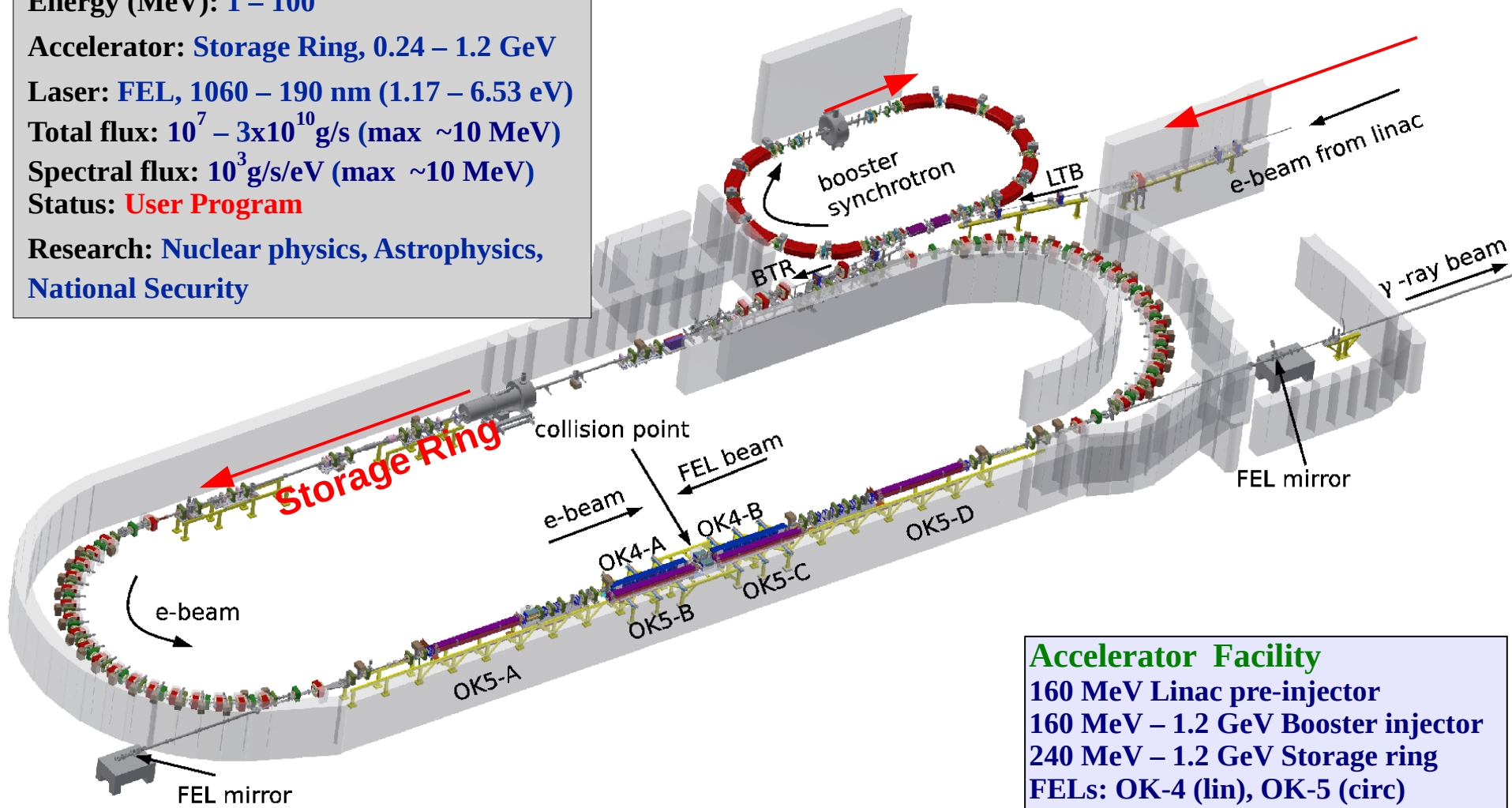
## JLab, CEBAF



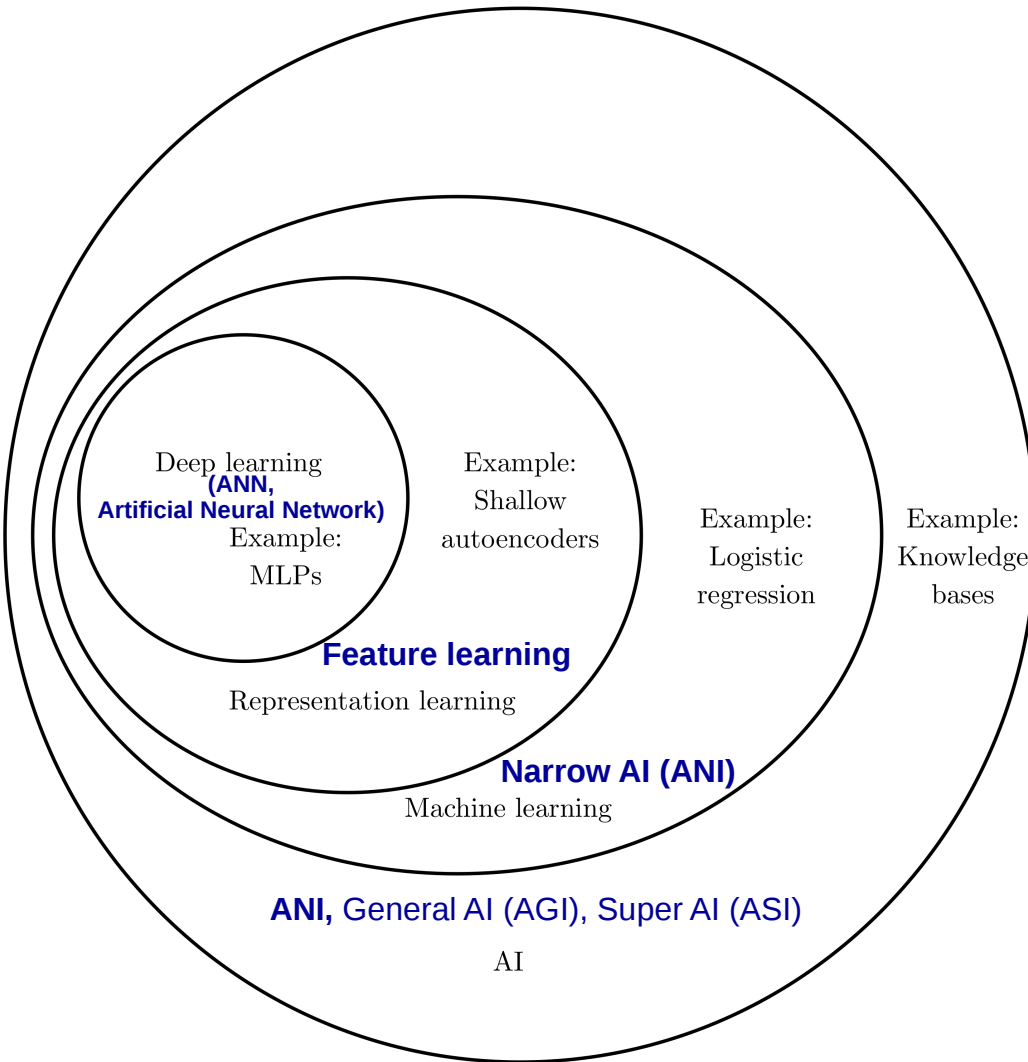
<https://science.osti.gov/np/Facilities/User-Facilities>  
[https://www.anl.gov/sites/www/files/2018-12/ATLAS\\_floor\\_plan\\_Dec2018.pdf](https://www.anl.gov/sites/www/files/2018-12/ATLAS_floor_plan_Dec2018.pdf)  
<https://www.jlab.org/physics>

Facility/Project: **HIGS**  
Institution: **TUNL and Duke University**  
Country: **US**  
Energy (MeV): **1 – 100**  
Accelerator: **Storage Ring, 0.24 – 1.2 GeV**  
Laser: **FEL, 1060 – 190 nm (1.17 – 6.53 eV)**  
Total flux:  **$10^7 - 3 \times 10^{10}$  g/s (max ~10 MeV)**  
Spectral flux:  **$10^3$  g/s/eV (max ~10 MeV)**  
Status: **User Program**  
Research: **Nuclear physics, Astrophysics, National Security**

## HIGS: an Electron-Photon Collider



**Accelerator Facility**  
160 MeV Linac pre-injector  
160 MeV – 1.2 GeV Booster injector  
240 MeV – 1.2 GeV Storage ring  
FELs: OK-4 (lin), OK-5 (circ)  
HIGS: two-bunch, 40 – 120 mA (typ)



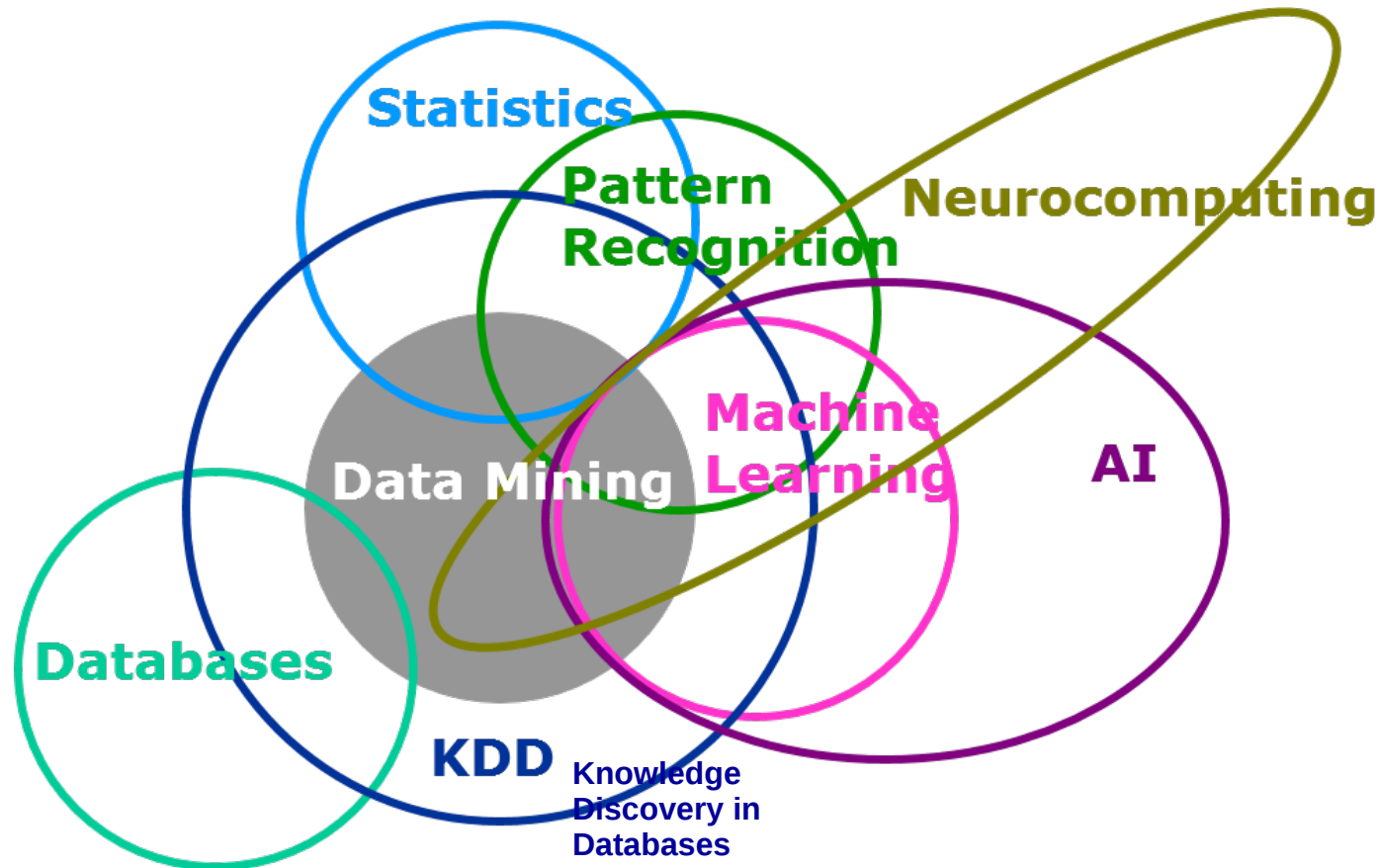
**Artificial Intelligence (AI):** The theory and development of computer systems able to perform tasks normally requiring human intelligence, such as visual perception, speech recognition, decision-making, and translation between languages.

**Machine learning (ML)** is the scientific study of algorithms and statistical models that computer systems use to perform a specific task without using explicit instructions, relying on patterns and inference instead. ML algorithms build a mathematical model based on sample data, known as "training data", in order to make predictions or decisions without being explicitly programmed to perform the task.

### ML → Narrow AI (ANI, part of Weak AI)

- Focus on a single/limited task
- Real-time response
- Based on a specific data set
- Cannot perform outside designed task
- Examples: IBM's Watson, Siri, Google Assistant/Translate, AlphaGo

## Learning from Data—Data-driven



SAS Institute, 1998

<https://blogs.sas.com/content/subconsciousmusings/2014/08/22/looking-backwards-looking-forwards-sas-data-mining-and-machine-learning/>

<https://www.analyticsvidhya.com/blog/2015/07/difference-machine-learning-statistical-modeling/>

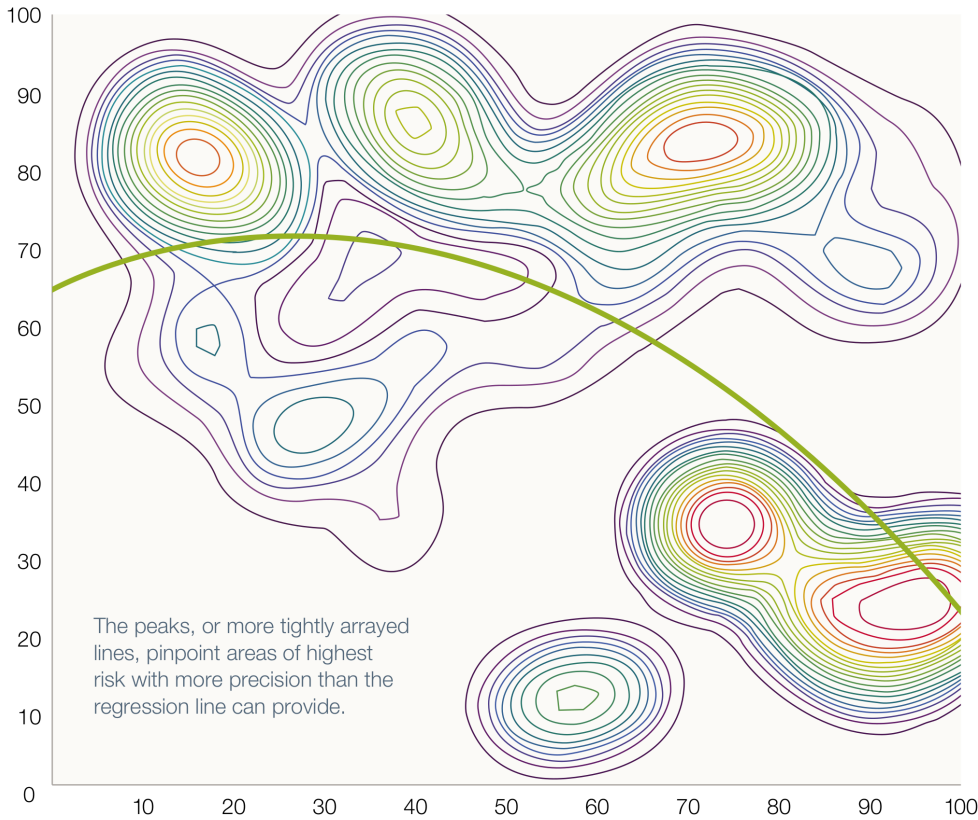
## Contrast between statistical analysis and machine learning

Value at risk from customer churn, telecom example

— Classic regression analysis

○ Isobar graph facilitated by machine learning: warmer colors indicate higher degrees of risk

Drivers: A



### Machine Learning:

An algorithm that can learn from data without relying on rules-based programming.

### Statistical Modeling:

Formalization of relationships between variables in the form of mathematical equations.

McKinsey&Company

McKinsey Quarterly, No. 3, 2015

Mathematical Models	Machine Learning
<p style="text-align: center;"><b>Advantages</b></p> <ul style="list-style-type: none"> <li>• Expert knowledge =&gt; good solutions rapidly</li> <li>• Input =&gt; Output with less computation</li> <li>• Exact solution possible</li> <li>• Reliable and consistent as constrained by model</li> <li>• First principle approach =&gt; better shield against algorithm bias</li> </ul>	<p style="text-align: center;"><b>Advantages</b></p> <ul style="list-style-type: none"> <li>• “Intelligence acquisition” with refinement automated</li> <li>• Account for things not considered originally, but happen regularly</li> </ul>
<p style="text-align: center;"><b>Disadvantages</b></p> <ul style="list-style-type: none"> <li>• Need expert knowledge and expert =&gt; requiring actual understanding of process and phenomenon Critical, rarely occurring details =&gt; model complexity Fine detail model =&gt; intense computation</li> <li>• Missing factors in the model: noise, drift, disruption, etc.</li> <li>• Less robust in real-world</li> </ul>	<p style="text-align: center;"><b>Disadvantages</b></p> <ul style="list-style-type: none"> <li>• In reality, automation is difficulty—training requires model tweaking by an expert</li> <li>• Need a lot of historical data</li> <li>• Model training is computation intensive</li> <li>• Results not often predictable</li> <li>• Solution may not be exact, with bias from the modelers</li> </ul>
<p><b>Example:</b>  <b>Predict where a baseball player would hit a ball</b></p> <ul style="list-style-type: none"> <li>• Build a math model using the laws of physics</li> <li>• Convert it to a computational model</li> <li>• Input: ball initial position, velocity, air resistance, etc.</li> <li>• Output: good prediction for where the ball will land</li> </ul>	<p><b>Example:</b>  <b>(The same baseball example)</b></p> <ul style="list-style-type: none"> <li>• Build a machine learning algorithm (model)</li> <li>• Feed in player’s previous data: input: pitch speed, placement, etc. outcome: where the ball landed</li> <li>• Use the model to predict an outcome of a new input</li> </ul>

## Types of ML Algorithms

- Supervised learning
- Unsupervised learning
- Reinforcement learning
- Self learning
- Feature learning
- Sparse dictionary learning
- Anomaly detection
- Association rules

## ML Models

- Artificial neural networks
- Decision trees
- Support vector machines
- Regression analysis
- Bayesian networks
- Genetic algorithms



## Areas of ML Applications for Particle Accelerators

“Opportunities in Machine Learning for Particle Accelerators,”

<https://arxiv.org/abs/1811.03172v1> (2018)

- **Anomaly detection and machine protection**
- **System Modeling**
- **Virtual Instrumentation / Virtual Diagnostics**
- **Tuning, Control, and Rapid Switching Between Operating Conditions**
- **Advanced Data Analysis**

Auralee Edelen, Christopher Mayes, Daniel Bowring, Daniel Ratner, Andreas Adelman, Rasmus Ischebeck, Jochem Snuverink, Ilya Agapov, Raimund Kammering, Jonathan Edelen, Ivan Bazarov, Gianluca Valentino, Jorg Wenninger, **Opportunities in Machine Learning for Particle Accelerators**, <https://arxiv.org/abs/1811.03172v1> (2018)

**ICFA beam dynamics mini-workshop: Machine learning applications for particle accelerators (SLAC, 2018)**

**2<sup>nd</sup> ICFA Workshop on Machine Learning for Charged Particle Accelerators (PSI, 2019)**

**ML-at-SLAC 1st Workshop (2019)**

## Areas of ML Applications for Particle Accelerators

“Opportunities in Machine Learning for Particle Accelerators,” <https://arxiv.org/abs/1811.03172v1> (2018)

### ■ Anomaly detection and machine protection

Acc. Problem	ML Technique; Data	Outcome	Notes
<ul style="list-style-type: none"> <li>• “Quench” detection: monitoring LHC SC magnets [1]</li> </ul>	<ul style="list-style-type: none"> <li>• Data: archived log resistive voltage data of SC magnets</li> <li>• <b>LSTM recurrent neural networks (RNN)</b></li> <li>• Long Short-Term Memory (LSTM) → long-range dependencies</li> <li>• Explore latent patterns of the data</li> </ul>	<ul style="list-style-type: none"> <li>• Predicting future voltage sequence: best RMSE=0.00104 (128 LSTM cells, 16 previous steps, batch size 2048)</li> <li>• Anomaly detection to be implemented using FPGA</li> <li>• Current system using pre-programmed triggers highly dependable</li> <li>• As an addition or enhancement</li> </ul>	<ul style="list-style-type: none"> <li>• Trained on common PC</li> <li>• Future use with FPGA (~kHz)</li> <li>• not used in operation</li> </ul>
<ul style="list-style-type: none"> <li>• “Quench” detection: monitoring XFEL SC RF cavity [2]</li> </ul>	<ul style="list-style-type: none"> <li>• Data: physics model based 2D residue data</li> <li>• <b>Support Vector Machine (SVM)</b> to find the 2D boundary</li> </ul>	<ul style="list-style-type: none"> <li>• Physics model based method works well: 100% accuracy with 5000 measurements</li> <li>• SVM is an addition and needs further improvement</li> </ul>	<ul style="list-style-type: none"> <li>• (2D linear system)</li> </ul>
<ul style="list-style-type: none"> <li>• Faulty <b>BPM</b> detection at LHC [3]</li> </ul>	<ul style="list-style-type: none"> <li>• Data: turn-by-turn BPM data</li> <li>• <b>Autoencoder:</b> Bad BPM has a higher loss</li> <li>• <b>Clustering:</b> Density-based spatial clustering</li> </ul>	<ul style="list-style-type: none"> <li>• Cannot be used alone</li> <li>• Used in addition to SVD analysis</li> </ul>	

[1] M. Wielgosz *et al.* “Using LSTM recurrent neural networks for monitoring the LHC superconducting magnets,” Nucl. Instrum. Meth. A867, 40–50 (2017),

[2] A.S. Nawaz *et al.* “Self-organized critical control for the european xfel using black box parameter identification for the quench detection system.” 2016 3rd Conference on Control and Fault-Tolerant Systems (SysTol). IEEE, 2016.

[3] E. Fol, and P. Henning. “Evaluation of machine learning methods for LHC optics measurements and corrections software”. Diss. Hochschule, Eng. Econ., Karlsruhe, 2017.

## Areas of ML Applications for Particle Accelerators

“Opportunities in Machine Learning for Particle Accelerators,” <https://arxiv.org/abs/1811.03172v1> (2018)

### ■ System Modeling

Acc. Problem	ML Technique; Data	Outcome	Notes
<ul style="list-style-type: none"> <li>Switch beam parameters in a THz FEL: <b>injector and beamline tuning</b> [1]</li> </ul>	<ul style="list-style-type: none"> <li>Data: simulated data including parameters of <b>RF, quadruples, Twiss parameters, emittance</b>, etc.</li> <li><b>Reinforcement learning</b> with two Neural Networks</li> </ul>	<ul style="list-style-type: none"> <li>In one iteration the controller can set up the machine to achieve close to the desired twiss parameters (initial study)</li> <li>Further study to optimize emittance and other parameters</li> </ul>	Sim. using Superfish and PARMELA
<ul style="list-style-type: none"> <li>Predicting beam parameters: <b>a gun injector</b> at Fermilab [2]</li> </ul>	<ul style="list-style-type: none"> <li>Data: simulated <b>solenoid</b> strengths, <b>gun</b> phases, and <b>cathode</b> images</li> <li>Hybrid of a <b>Convolutional Neural Network (CNN)</b> and a fully-connected NN</li> </ul>	<ul style="list-style-type: none"> <li>Predicting downstream twiss parameters, emittance, etc.</li> <li>Mean errors between 0.4% and 3.1% of the parameter ranges</li> </ul>	Sim. using Superfish and PARMELA; Plan to train the model using measured data.

[1] A.L. Edelen, *et al.* “Using a neural network control policy for rapid switching between beam parameters in an FEL”. Proceedings of the 38th International Free Electron Laser Conference (2017)

[2] A.L. Edelen, *et al.* “First steps toward incorporating image based diagnostics into particle accelerator control systems using convolutional neural networks”. arXiv preprint arXiv:1612.05662 (2016).

## Areas of ML Applications for Particle Accelerators

“Opportunities in Machine Learning for Particle Accelerators,” <https://arxiv.org/abs/1811.03172v1> (2018)

### Virtual Instrumentation / Virtual Diagnostics

Acc. Problem	ML Technique; Data	Outcome	Notes
<ul style="list-style-type: none"> <li>Predicting X-ray FEL pulse properties at LCLS [1]</li> </ul>	<ul style="list-style-type: none"> <li>Data from single-shot diagnostics (fast and slow) for electron beam and X-ray</li> <li>Linear, Quadratic, <b>Support Vector Regression (SVR)</b>, <b>ANN</b></li> </ul>	<ul style="list-style-type: none"> <li>Energy mean error below 0.3 eV (for 530 eV photon); pulse delay below 1.6 fs; spectral shape agreement at 97%</li> <li>Applicable to predict for each shot of XFEL at MHz</li> </ul>	<p>Tested with exp. data</p>
<ul style="list-style-type: none"> <li>Prediction of electron beam longitudinal phase space (LPS)/current profile at (1) FACET-II and (2) LCLS [2]</li> </ul>	<ul style="list-style-type: none"> <li>Multilayer perceptron (<b>MLP</b>) regressor from scikit-learn (an open source ML library)</li> <li>Data for training and validation: from simulated non-intercepting diagnostics and LPS images for FACET-II; five nondestructive measurements and LPS images measured using a transverse deflecting cavity for LCLS</li> </ul>	<ul style="list-style-type: none"> <li>Predicting electron beam shot-to-shot 2D LPS (nondestructive)</li> <li>Prediction performance depends critically on the accuracy and resolution of diagnostic inputs</li> <li>Good agreement between the predicted and simulated/measured LPS profiles</li> </ul>	<p>Simu. and Exp.</p>

[1] A. Sanchez-Gonzalez, *et al.* “Accurate prediction of X-ray pulse properties from a free-electron laser using machine learning”. Nature communications 8.1 (2017): 1-9.

[2] C. Emma *et al.* “Machine learning-based longitudinal phase space prediction of particle accelerators.” Phys. Rev. Accel. and Beams 21, 112802 (2018).

## Areas of ML Applications for Particle Accelerators

“Opportunities in Machine Learning for Particle Accelerators,” <https://arxiv.org/abs/1811.03172v1> (2018)

### • Tuning, Control, and Rapid Switching Between Operating Conditions

Acc. Problem	ML Technique; Data	Outcome	Tech.
<ul style="list-style-type: none"> <li>Switch beam parameters in a THz FEL: <b>injector and beamline tuning</b> [1] (Also in System Modeling)</li> </ul>	<ul style="list-style-type: none"> <li><b>Neural networks</b> trained by <b>reinforcement learning</b></li> <li>Data from PARMELA simulation</li> </ul>	<ul style="list-style-type: none"> <li>Encouraging results: with 1 iteration the controller can achieve close to the correct Twiss parameters for test beam with energies in 3–6 MeV</li> </ul>	Simu.
<ul style="list-style-type: none"> <li>Online <b>undulator tapering</b> optimization at LCLS [2]</li> </ul>	<ul style="list-style-type: none"> <li><b>NN with reinforcement learning</b></li> <li>Other techniques: Robust Conjugate Direction Search (RCDS); Mutil-Object Genetic Algorithm (MOGA); Particle Swarm Optimization (PSO); Extreme Seeking (ES); Simulated Annealing (SA); Markov Chain Monte Carlo (MCMC)</li> </ul>	<ul style="list-style-type: none"> <li>Optimal zig-zag taper, the pulse energy of 5.5 keV self-seeded FEL is <b>doubled</b></li> </ul>	Exp.
<ul style="list-style-type: none"> <li>Tuning <b>quad settings</b> of LCLS beamline [3]</li> <li>Noise issue in optimization and to incorporate physics model</li> </ul>	<ul style="list-style-type: none"> <li><b>Bayesian optimization</b> using <b>Gaussian Process</b></li> <li>Existing technique: Nelder-Mead optimization</li> <li>Hyperparameters generated using historical data</li> </ul>	<ul style="list-style-type: none"> <li>Prelim results:</li> <li>achieve faster optimization than hand tuning and other optimization methods</li> <li>Bayesian optimization depends strongly on hyperparameters</li> </ul>	Exp.

[1] A.L. Edelen et al. “Using a neural network control policy for rapid switching between beam parameters in an fel,” pp. 406-409, Proceedings of FEL2017.

[2] J. Wu et al. “Recent On-Line Taper Optimization on LCLS,” p. 229, Proceedings of FEL2017.

[3] M. McIntire et al. “Bayesian Optimization of FEL Performance at LCLS,” p. 2972, Proceedings of IPAC2016.

## Areas of ML Applications for Particle Accelerators

“Opportunities in Machine Learning for Particle Accelerators,” <https://arxiv.org/abs/1811.03172v1> (2018)

### • Tuning, Control, and Rapid Switching Between Operating Conditions

Acc. Problem	ML Technique; Data	Outcome	Tech.
<ul style="list-style-type: none"> <li>Temperature control of <b>cooling water</b> for a normal conducting <b>RF gun</b> [1] at Fermilab</li> <li>Goal: +/- 0.02 K</li> </ul>	<ul style="list-style-type: none"> <li>Model-based predictive control (<b>MPC</b>); linearized</li> <li>A rudimentary <b>neural network</b> used to relate cavity temp. to input water temp.</li> </ul>	<ul style="list-style-type: none"> <li>Reaching +/- 0.02K control in 5 minutes vs ~23 min using the existing feedforward/PI controller</li> </ul>	Exp. (no RF power)
<ul style="list-style-type: none"> <li>Cooling control for a <b>RFQ</b> [2] at Fermilab</li> </ul>	<ul style="list-style-type: none"> <li>Model-based predictive control (<b>MPC</b>)</li> <li><b>Neural network</b>: Input: water temperatures at various locations, water flow rates, ambient temp. and humidity; Output: RFQ resonant frequency</li> </ul>	<ul style="list-style-type: none"> <li>Neural network model performs well in predicting the RFQ resonant frequency due to changes in the cooling system and amount of RF heating</li> <li>More training for other operation modes, and with finer granularity</li> </ul>	Exp. (pulsed operation)
<ul style="list-style-type: none"> <li><b>Ion source</b> control for RFT-30 cyclotron at KAERI</li> <li>Highly nonlinear and complex</li> </ul>	<ul style="list-style-type: none"> <li><b>Artificial neural network</b> based ion source model</li> <li>Generalized predictive control (<b>GPC</b>)</li> <li><b>Simulated annealing algorithm</b></li> </ul>	<ul style="list-style-type: none"> <li>Found a subset of ion source parameters, but already an efficient way to control and analyze the source</li> <li>Will train the ion source model with diverse experimental data</li> </ul>	Simu. using exp data

[1] A.L. Edelen et al. “Initial experimental results of a machine learning-based temperature control system for an RF gun,” p. 1217, Proceedings of IPAC2015.

[2] A. Edelen et al. “Neural Network Model Of The PXIE RFQ Cooling System and Resonant Frequency Response,” p. 4131, Proceedings of IPAC2016.

[3] Y.B. Kong et al. “Predictive ion source control using artificial neural network for rft-30 cyclotron,” NIM A806, p. 55 (2016).

## Areas of ML Applications for Particle Accelerators

“Opportunities in Machine Learning for Particle Accelerators,” <https://arxiv.org/abs/1811.03172v1> (2018)

### ■ Advanced Data Analysis

Acc. Problem	ML Technique; Data	Outcome	Technology
<ul style="list-style-type: none"> <li>Measuring muon phase space volume change at MICE [1]</li> </ul>	<ul style="list-style-type: none"> <li>Data: simulated data including the muon parameters and a <b>LiH absorber</b></li> <li><b>Kernel Density Estimation (KDE)</b></li> </ul>	<ul style="list-style-type: none"> <li>Observed changes of phase space density and volume</li> </ul>	Sim. using MAUS and G4beamline
<ul style="list-style-type: none"> <li>Study of the short electron bunch longitudinal dynamics/ microbunching instability due to the emitted THz coherent synchrotron radiation (CSR) in storage ring KARA [2]</li> </ul>	<ul style="list-style-type: none"> <li>Clustering using the <b>k-means method</b></li> <li>Four clusters in the longitudinal bunch profiles</li> <li>Each profile with a cluster label is mapped to a CSR power in time sequence</li> <li>Data for training and validation: simulation based on the Vlasov-Fokker-Planck equation</li> </ul>	<ul style="list-style-type: none"> <li>Discovery of a correlation between the electron bunch longitudinal micro-structure and the emitted CSR power</li> <li>Indication of dependencies of the micro-structure properties on various machine parameters such as beam current, synchrotron frequency, and vacuum gap.</li> </ul>	Simu.

[1] T.A. Mohayai, P. Snopok, and D. Neuffer. “A Non-Parametric Density Estimation Approach to Measuring Beam Cooling in MICE”. arXiv preprint arXiv:1806.01834 (2018).

[2] T. Boltz *et al.* “Studies of longitudinal dynamics in the micro-bunching instability using machine learning.” IPAC2018, THPAK030.

## **Observations:**

- **Many ML models and algorithms have been explored**
- **Successful ones typically involve well-defined problems and/or small systems with limited complexity**
- **As an add-on or improvement to existing techniques/methods**
- **Many have not yet been used for real-time applications**

## **Opportunities to Advance/Expand Machine Learning using Particle Accelerators**

- **A new type of machine learning centered around complex physical systems — the accelerator, not only the data, plays a critical or even dominant role**
  - **Develop more powerful machine learning techniques by combining physics knowledge and data models**
  - **Take advantage of a rich set of realtime information from accelerator operation**